

# Resolving Indirect Jumps for Dynamic Instrumentation Applications

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# What is binary instrumentation?

Allow an application to be instrumented **without recompiling from source** by inserting the instrumentation **before** or **during** the execution.

- ▶ Don't rely on static instrumentation that needs recompilation
- ▶ Quick instrumentation and prototyping
- ▶ Some application don't have static tracepoint already implemented

# Binary instrumentation methods

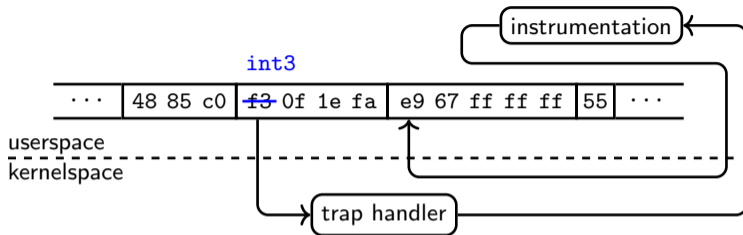


Figure: trap-based dynamic instrumentation

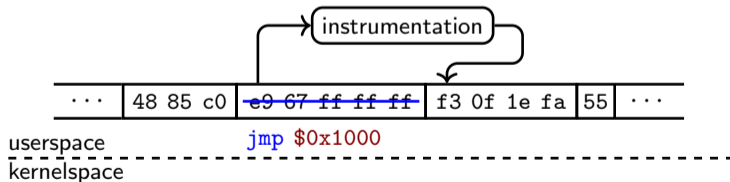
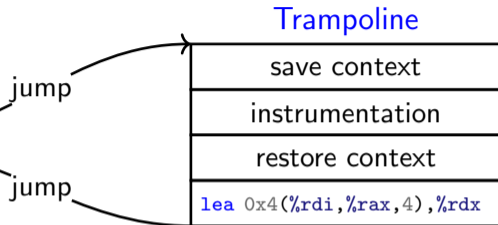


Figure: jump-based dynamic instrumentation

## Jump-based binary instrumentation (example 1)

```
test  %esi,%esi
jle   0x20
lea   -0x1(%rsi),%eax
/* what is the value of %eax? */
lea  0x4(%rdi,%rax,4),%rdx
xor   %eax,%eax
xchg  %ax,%ax
add   (%rdi),%eax
add   $0x4,%rdi
cmp   %rdx,%rdi
jne   0x10
retq
nopl  0x0(%rax)
xor   %eax,%eax
retq
```



48 8d 54 87 04      lea 0x4(%rdi,%rax,4),%rdx

could be replaced by

e9 fb 0f 00 00      jmp \$0x1000

## Jump-based binary instrumentation (example 2)

```
test  %esi,%esi
jle   0x20
lea   -0x1(%rsi),%eax
lea   0x4(%rdi,%rax,4),%rdx
/* what is the value of %rdx? */
xor  %eax,%eax
xchg %ax,%ax
add  (%rdi),%eax
add   $0x4,%rdi
cmp   %rdx,%rdi
jne   0x10
retq
nopl  0x0(%rax)
xor   %eax,%eax
retq
```

jump

jump

### Trampoline

save context

instrumentation

restore context

```
xor  %eax,%eax
xchg %ax,%ax
add  (%rdi),%eax
```

31 c0

xor %eax,%eax

66 90

xchg %ax,%ax

03 07

add (%rdi),%eax

could be replaced by

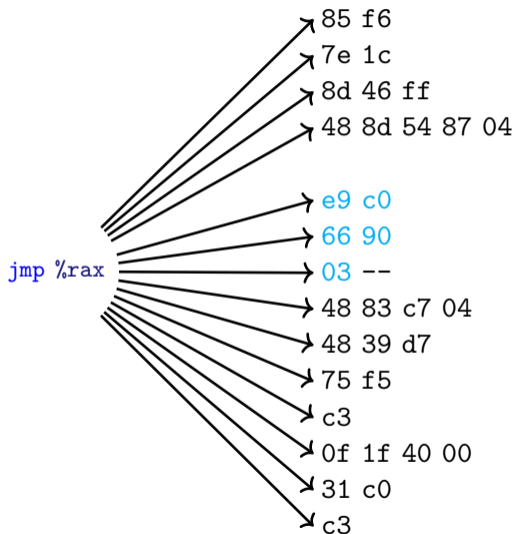
e9 fb

jmp \$0x1000

0f 00

00 --

## The indirect jump problem



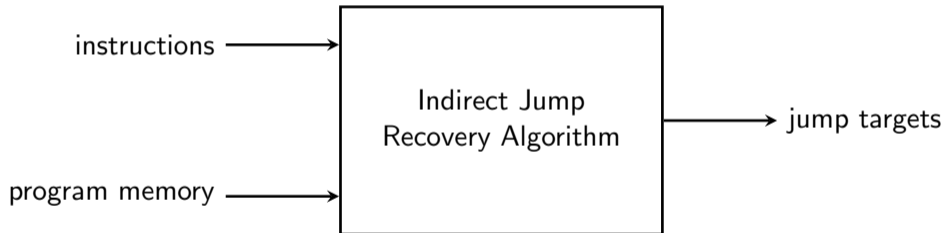
```
test  %esi,%esi
jle   0x20
lea   -0x1(%rsi),%eax
lea   0x4(%rdi,%rax,4),%rdx
/* what is the value of %rdx? */
jump  $0x1000

add   $0x4,%rdi
cmp   %rdx,%rdi
jne   0x10
retq

nopl  0x0(%rax)
xor   %eax,%eax
retq
```

## Goal of the work

The goal of the work is to have an algorithm that can compute indirect jump target addresses.



# What can generate indirect jumps?

## *switch cases*

```
switch (n) {  
case 0: m = 3; break;  
case 1: m = 6; break;  
case 2: m = 1; break;  
case 3: m = 2; break;  
case 4: m = 9; break;  
case 5: m = 7; break;  
case 6: m = 2; break;  
default: break;  
}
```

```
# %rax = n  
cmp $6,%rax  
ja 0x152  
mov JUMP_TABLE(,%rax,8),%rbx  
jmp *%rbx
```

## *tail-optimized indirect call*

```
void call(void (*f)(void)) {  
    /* ... */  
    /* ... */  
    /* ... */  
    f();  
}
```

```
# %rsi = f  
jmp *%rsi
```

## *tail-optimized virtual call*

```
class base {  
public:  
    virtual foo();  
};  
  
void call(base& base) {  
    /* ... */  
    /* ... */  
    /* ... */  
    base.foo();  
}
```

```
# %rdi = base  
mov (%rdi),%rax  
jmpq *(%rax)
```



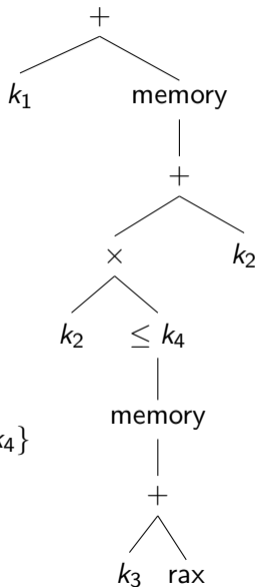
## Current solutions

- ▶ Reverse engineering tools already try to recover the whole control-flow graph, thus also indirect jumps.
  - ▶ e.g. [Radare2](#), [Ghidra](#), [IDA Pro](#)
  - ▶ The two first failed to recover indirect jumps in my testing.
  - ▶ Usually goes through all the instructions in a top to bottom fashion.
- ▶ [Expression substitution technique](#) similar to method 1.

## Method 1 – Reconstructing the computation

```
cmpl  $4,20(%rax)
ja    1337
mov   20(%rax),%eax
lea   1000(%rip),%rbx
movslq(%rbx,%rax,4),%rax
mov   %rax,%rdx
add  %rbx,%rax
jmpq  *%rax
```

targets =  $\{k_1 + \text{memory}(k_2 + k_3 \times i) \mid 0 \leq i \leq k_4\}$



## Validating recovered jump results

- ▶ Manual validation:
  - ▶ Compile with `gcc -S` to get assembly.
  - ▶ Dump assembly with `objdump -D`.
  - ▶ Manually compare the results.
  - ▶ Very time consuming.
  
- ▶ Automatic validation:
  - ▶ Somehow modify `gcc` to output additional informations.
  - ▶ Have a script do the validation.
  - ▶ Very few knowledge in compiler.

# Simple GCC patch

```
diff --git a/gcc/final.c b/gcc/final.c
index a3601964a8d..93f266d408b 100644
--- a/gcc/final.c
+++ b/gcc/final.c
@@ -2507,6 +2507,7 @@ final_scan_insn_1 (rtx_insn *insn, FILE *file, int optimize_p ATTRIBUTE_UNUSED,

#ifdef ASM_OUTPUT_CASE_LABEL
    ASM_OUTPUT_CASE_LABEL (file, "L", CODE_LABEL_NUMBER (insn), table);
+   targetm.asm_out.internal_label (file, "JUMP_TABLE_START", CODE_LABEL_NUMBER(insn));
#else
    targetm.asm_out.internal_label (file, "L", CODE_LABEL_NUMBER (insn));
#endif
@@ -2621,6 +2622,7 @@ final_scan_insn_1 (rtx_insn *insn, FILE *file, int optimize_p ATTRIBUTE_UNUSED,
#endif
    }
+   targetm.asm_out.internal_label (file, "JUMP_TABLE_END", CODE_LABEL_NUMBER (PREV_INSN(insn)));
#ifdef ASM_OUTPUT_CASE_END
    ASM_OUTPUT_CASE_END (file,
        CODE_LABEL_NUMBER (PREV_INSN(insn)),
```

## Simple GCC patch – Results

```
# the jump computation
cpl      $6, -4(%rbp)
ja       .L10
movl     -4(%rbp), %eax
leaq    0(,%rax,4), %rdx
leaq    .L12(%rip), %rax
movl     (%rdx,%rax), %eax
cltq
leaq    .L12(%rip), %rdx
addq    %rdx, %rax
jmp     *%rax

# the jump table
.section      .rodata
.align 4
.align 4
.L12:
.JUMP_TABLE_START12:
        .long      .L19-.L12
        .long      .L21-.L12
        .long      .L22-.L12
        .long      .L23-.L12
        .long      .L24-.L12
        .long      .L25-.L12
        .long      .L26-.L12
.JUMP_TABLE_END12:
```

## Implementation

The proof of concept was done in Python with `capstone` disassembler.

To add the feature into a dynamic tracing implementation, only a single “if” needs to be modify with the algorithm.

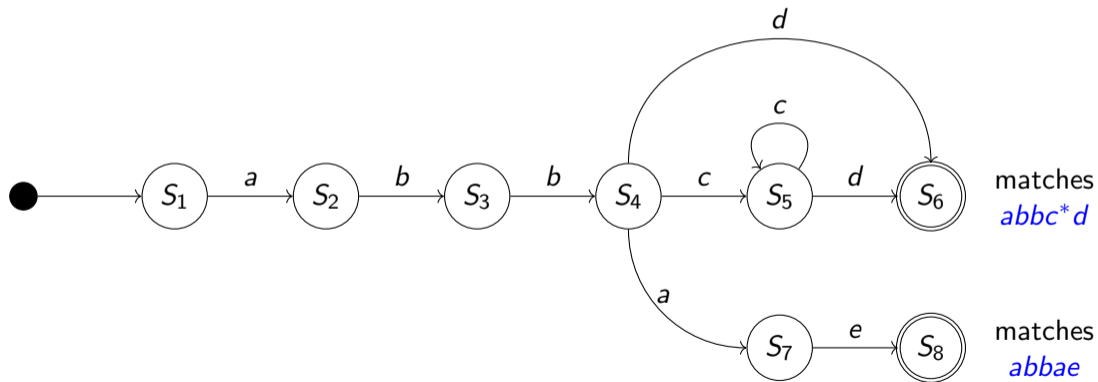
- ▶ `uftrace` – userspace function tracer
  - ▶ `check_unsupported` @ [arch/x86\\_64/mcount-insn.c](#)
  - ▶ already uses `capstone` disassembler
- ▶ `kprobe` – linux kernel
  - ▶ `can_optimize` @ [arch/x86/kernel/kprobes/opt.c](#)
  - ▶ more complex and time consuming to develop

## Method 1 – Results

- ▶ It is complex and hard to maintain
- ▶ Current implementation fails to recover some pattern
- ▶ On `git` binary, `uftrace` now patches 94% compared to previous 90%
  - ▶ Most of the 6% isn't due to indirect jump
  - ▶ The rest is unsupported patterns

## Method 2 – Pattern Matching

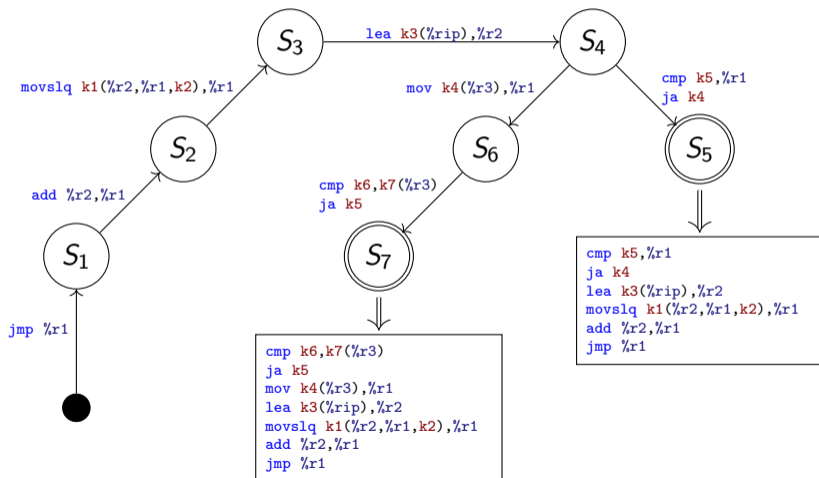
Regular expressions are efficient thanks to the compilation process which generates a state machine that can test a string in linear time.





## Method 2 – Pattern Matching

By applying this concept, we can pattern match instructions and test a given sequence of instructions in linear time.



## Method 2 – Pattern Matching

This method aims to

- ▶ reduce complexity (both in performance and understanding) and
- ▶ ease the addition of new patterns.

Right now,

- ▶ the proof of concept is basically done,
- ▶ some implementation details need to be sorted and
- ▶ it is almost implemented in `uftrace`.

Questions?