

## **NOPROBE: A Fast Multi-strategy Probing Technique For x86 Dynamic Binary Instrumentation**

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Summary

## 1. Introduction

- 2. Literature review
- 3. Problem definition
- 4. Proposed Solution

## 5. Results

6. Conclusion





□ The what and why...

❑ Static:

□Added before/during compilation

Dynamic:

During the execution

□Agent injected in process address space



### 1. Introduction x86-ISA

□ x86 variable instruction size

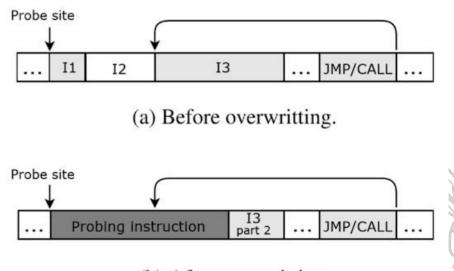
□Reason: performance and compression.

Dynamic Binary instrumentation (code injection with instr replacement)

□branch (CALL / JMP) vs Trap (INT3)

□ Instructions border changes:

- □ Jump to an invalid border.
- Return from preemption, interruption, or blocked state to an invalid border.



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(b) After overwritting.

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# 2. Literature review

### Dynamic binary instrumentation in

user-space

### 2. Revue de la littérature

**Uprobe**: Trap instruction (flexible but too slow)

**GDB**: Trap instruction (with ptrace => slower than *uprobe*)

- □ Fast tracepoint: A branch with a limit on the instrumented instr size
- Seek quiescence by stopping the world

**Dyninst:** Uses Control-Flow Graph (CFG) => flexible and very fast

Too much intrusion: high memory usage, stop the world (more than
 5s in 64 cores machine), high computation during the insertion.

**Uvalgrind and Pin:** Intermediate representation (IR) in a VM.

□ Very slow execution (up to x100 slower for Valgrind)

Liteinst and Dyntrace: A branch probe that embed traps in it's offset

- Fast in most cases, but could worst than trap-based probes in some cases (loop)
- □ Fragment the memory. Badly supported in x86\_32 (4Go addr

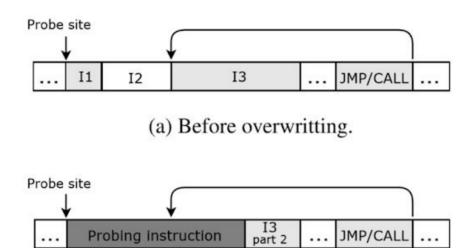
space). *Dyntrace*: Unsafe on-the-fly instrumentation.

# **3.** Problem definition

### 3. Problem definition

□ Simultaneous execution problem:

Due to instruction borders changes



(b) After overwritting.

#### $\hfill \mathsf{P}\mathsf{erformance}$ and memory usage

### 3. Problem definition

□ Out-of-line execution: Support as many instruction relocation as possible

(Target out of reach, invalid relative address).

□ Intel Cross/Self Modification:

During execution, patching code that overlaps cache lines may not

be atomic and can cause a GPF.

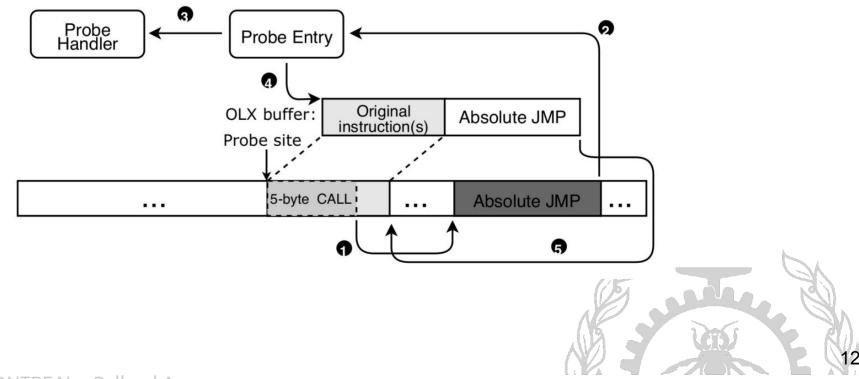
□Intel errata: A core should execute a serializing instruction (CPUID,

IRET, etc..) prior to new code execution.



□NOProbe: A dynamic instrumentation solution

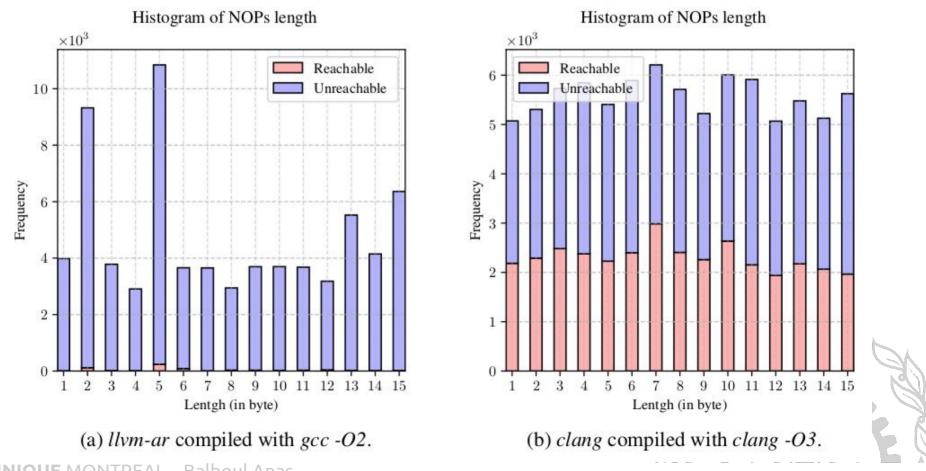
□First strategy:



□**NOP-padding** added by default during compiler optimization starting from level 2 for GCC and level 3 for Clang.

□ They are everywhere !

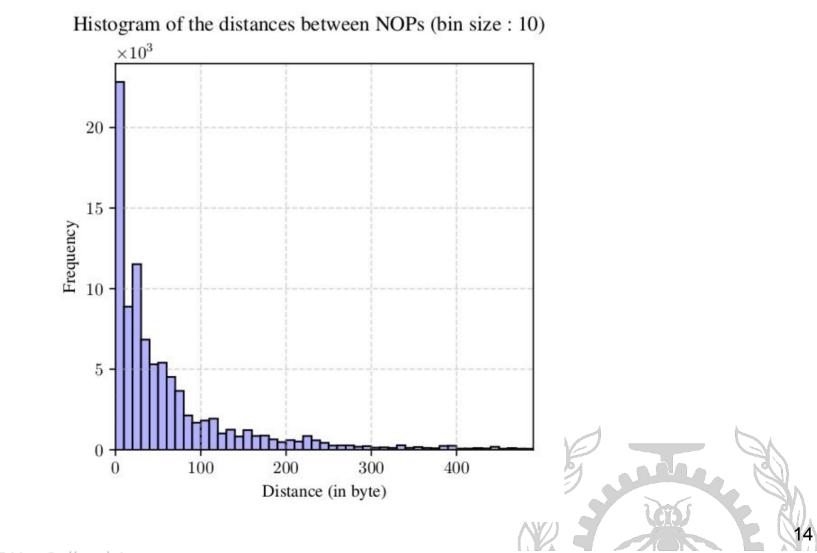
□percentage of reachable and unreachable NOPs in two samples:



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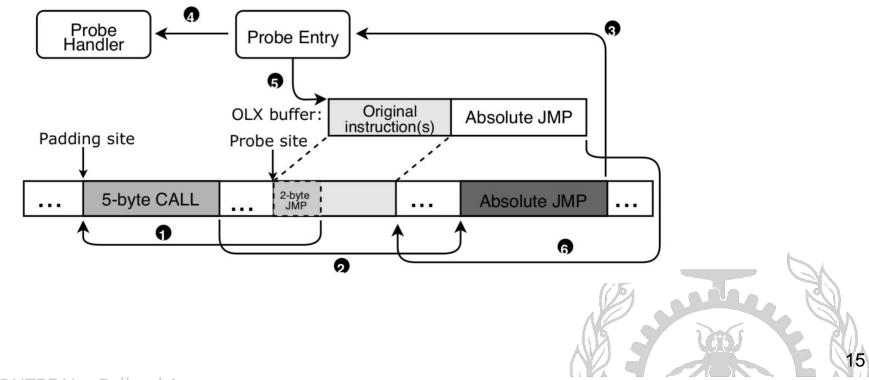
□NOP distribution analysis

□Histogram of distances between NOPs:



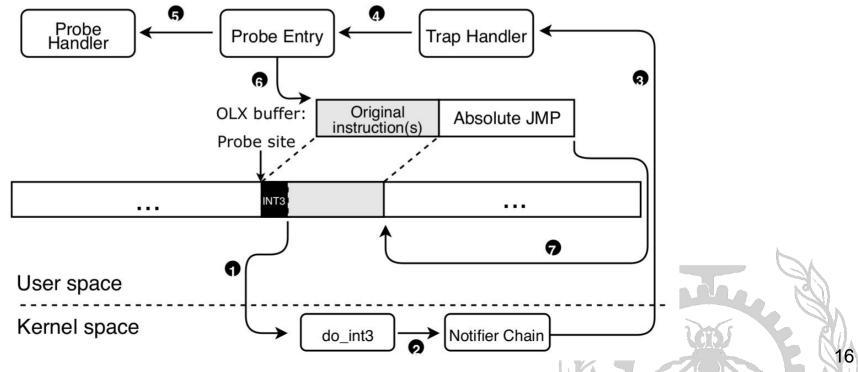
□NOProbe: A dynamic instrumentation solution

□Second Strategy:



□NOProbe: A dynamic instrumentation solution

□Third and last resort strategy:



→NOProbe: Static Analysis:

□Which strategy to deploy:

Disassemble the probed function and check the target of each branch...

□To find out if a NOP is reachable or not:

- The function size in the ELF symbol table is used to find NOPs that align functions.
- □ NOPs aligning jumps, loops and labels have a pattern:

```
000000000027a00 <free_parsed_cmdline>:
      48 8b 7f f8
27a09:
                                 -0x8(%rdi),%rdi
                          mov
27a20:
      f3 c3
                         repz retq
27a22: 0f 1f 40 00
                         nopl 0x0(%rax)
27a26:
      66 2e 0f 1f 84
                        nopw %cs:0x0(%rax,%rax,1)
        00 00 00 00 00
                                        000000000015610 <do_replay>:
000000000027a30 <absolute_dirname>:
                . . .
                                        15763:
                                                Of 88 d7 00 00 00
                                                                           15840 <do_replay
                                                                      js
                                                89 30 ff ff ff
                                                                           15769 <do_replay
                                        15833:
                                                                      jns
                                                                                          17
                                                                      nopl 0x0(%rax)
                                        15839:
                                                1f 80 00 00 00 00
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                                        15840:
                                                83 c4 01
                                                                      add
                                                                           $0x1, %r12d
```

	Assembl	y (AT&T Syntax)	Byte Sequence (Hexadecimal)			
<ul> <li>Proposed Solution</li> <li>OProbe: Reachable NOP:</li> <li>The program could execute them</li> </ul>	nopw 0x nopl 0x0 nopl 0x0 nopw 0x	ax) (%rax) (%rax,%rax,1) 0(%rax,%rax,1)	90 66 90 0f 1f 00 0f 1f 40 00 0f 1f 44 00 00 66 0f 1f 44 00 00 0f 1f 80 00 00 00 00 0f 1f 84 00 00 00 00 66 0f 1f 84 00 00 00 00 00			
Carefully patch them						
□We need 5 bytes for the trampoline	е					
0: 0f 1f 80 00 00 00 00 7: 48 89 c8		RD PTR [rax+0), rcx	<0]			
0: eb 04 jmp 2: e8 01 02 03 04 call 7: 48 89 c8 mov	0x6 0x4030208 rax,rcx					
0: 0f 1f 84 00 nop 1	DWORD PTR	[rax+rax*1+	0x0]			
00 00 00 00						

□NOProbe: Assigning NOPs to probes:

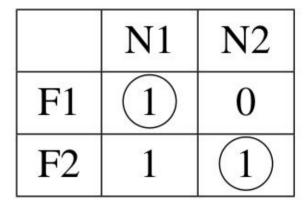
□Optimal solution (Hungarian):

□ Complexity O(n<sup>3</sup>)

□Greedy algorithm:

A two bytes JMP has one byte offset and can go 128/127 bytes back and forth.

□ Prioritize the closed NOP to a probe.





#### □NOProbe: Out-of-Line eXecution (OLX):

5-byte JMP, JCC (conditional jump) and CALL have an offset of 4 bytes
They can only reach 2Go in both directions (problematic in x86\_64)
They are relocated this way:

0: e9 12 34 56 78 jmp 0x78563417

(a) Before relocation.

0: ff 25 00 00 00 00 jmp QWORD PTR [rip+0x0] 6: 00 00 00 00 17 34 data target address 56 78

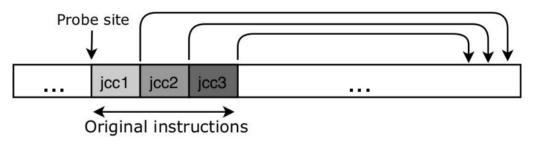


□NOProbe: Out-of-Line eXecution (OLX):

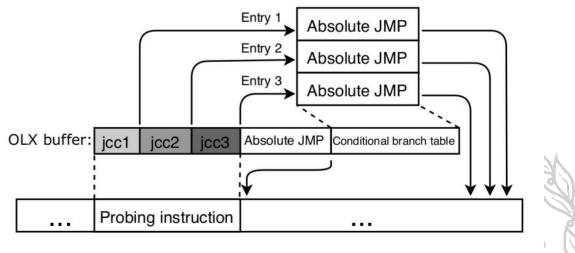
□2-byte JMP, JCC (conditional jump) have an offset of 1 byte

They can only reach 127/128 bytes in both directions

They are relocated this way:



(a) Before relocation.



(b) After relocation.

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□NOProbe: Out-of-Line eXecution (OLX):

□RIP relative addressing (added in x86\_64)

□Relative address is invalid after relocation:

They are relocated this way: (inspired from uprobe and adapted to user space)

site+0: cmp rdx, QWORD PTR [rip+0x5]

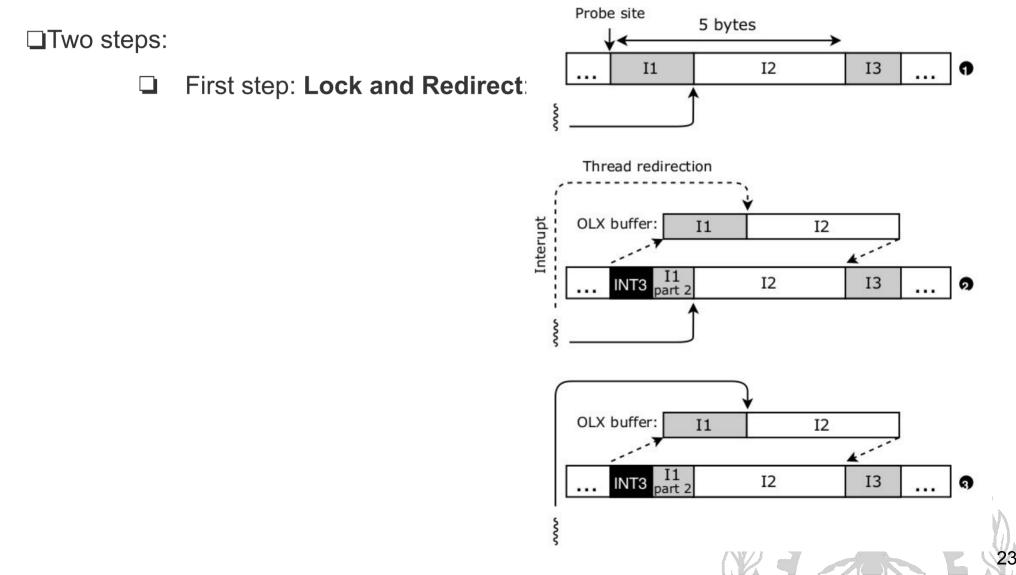
(a) Before relocation.

olx+0:	push	rax	
olx+1:	mov	rax,	0x00000000000000000000
olx+b:	cmp	rdx,	QWORD PTR [rax]
olx+c:	pop	rax	

(b) After relocation.



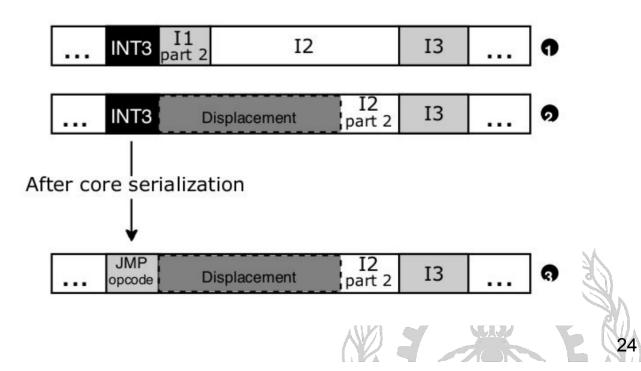
□NOProbe: Lock and Load: On-the-fly patching without stopping the program



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□Two steps:

- Second step: Load and Arm:
  - □ When available: Core serialization with membarrier (the syscall)
  - □ Else: real-time signal to execute CPUID.



□NOProbe: Signal Dispatching:

□We use two signals

- □ SIGTRAP:
  - When locking the patching area
- Real-time signal
  - □ When redirecting the threads outside the patching area

□We avoid exclusive usage by sharing them

□How we do it ? we Intercept sigaction(), signal(), et sigprocmask() :

- Save the signal handler and signal masks in user space instead of registering them.
- We register our own trap handler that dispatch the signal to the saved handler registered by the program or to the instrumentation signal handler (based on the TID for real-time signal, and based on the address of the raised trap for SIGTRAP).



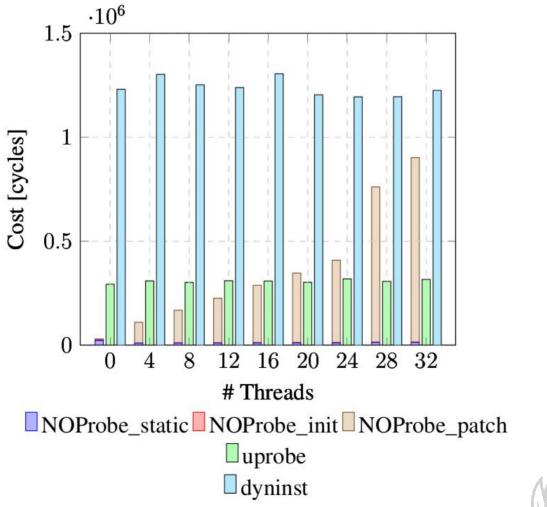
□ Specification of the test machine:

Processor	4x Intel Xeon E7-8867 v3 @2.50GHz
# Cores	64 with Hyper-Threading disabled
Operating System	Debian GNU/Linux 9.0 and Linux 4.19.0-6-amd64
Compiler & Libraries	GCC/G++ 8.3.0 and GLIBC 2.28-10
Virtualization	Kernel-based Virtual Machine
Memory	256GB



□ Instrumentation Installation cost:

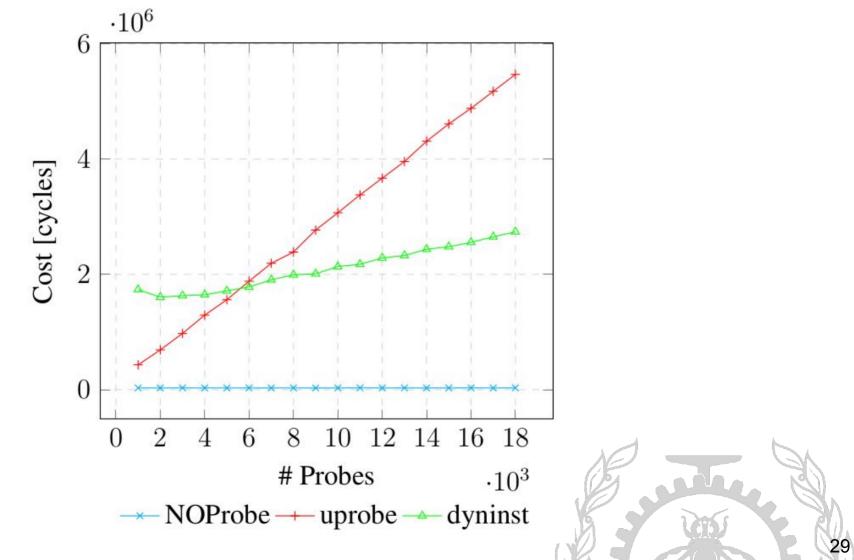
□VS the <u>number of executing thread:</u>





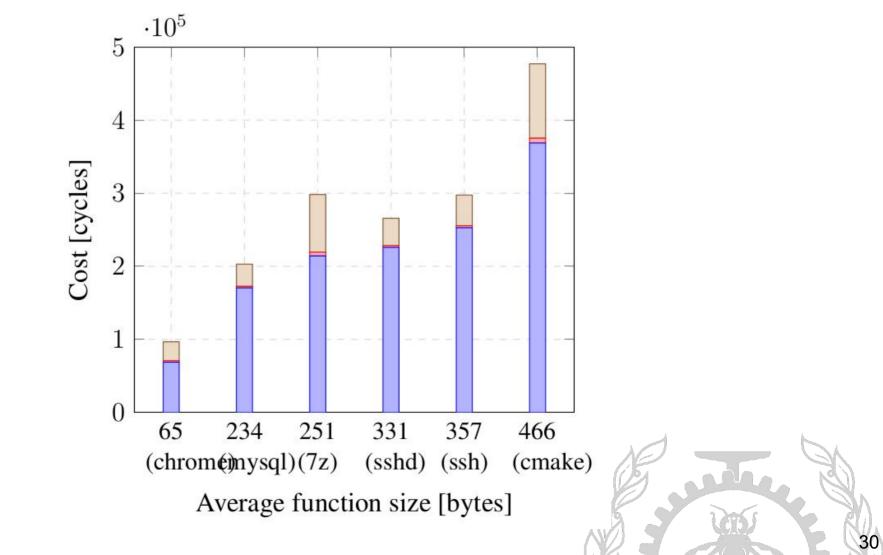
□ Instrumentation Installation cost:

□VS the <u>number of installed probes</u>:



□ Instrumentation Installation cost:

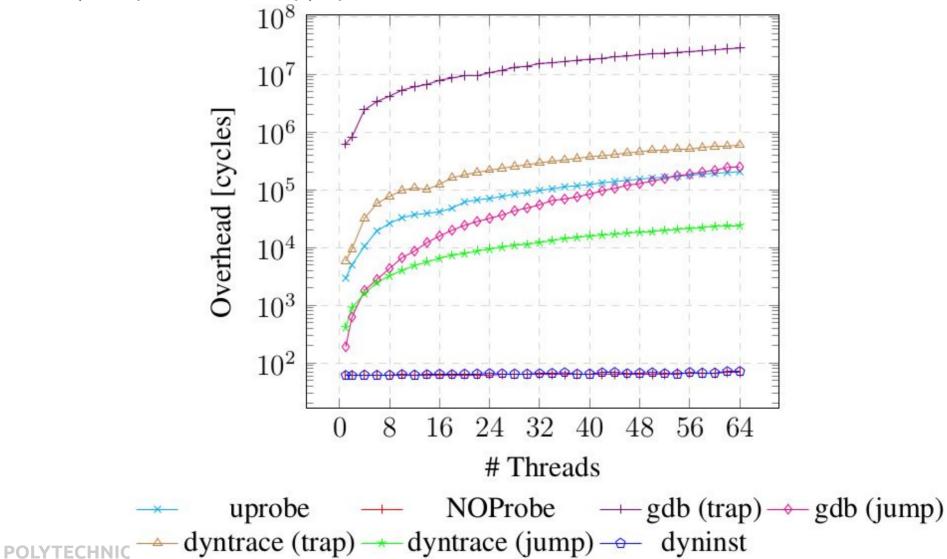
□VS the <u>average function size</u>:



#### Execution cost:

□For probe insertion in a red and black tree, NOProbe avoid using costly locks and CAS

(Compare And Swap) operations.





#### □ Probe effectiveness

Defined as: successful fast (branch) probes insertion ratio:

	GDB		NOProbe		Dyntrace			Dyninst				
Bench	Success	Total	Rate	Success	Total	Rate	Success	Total	Rate	Success	Total	Rate
chrome	28982	326205	8.88%	310497	326205	95.18%	-	-		320216	326205	98.16%
llvm-ar	523	19940	2.2%	19104	19940	95.80%	9318	19940	46.73%	75539	75539	100%
git	1	9901	0.01%	9815	9901	99.13%	4291	9900	43.34%	9908	9908	100%
vim	0	6396	0%	6279	6396	98.17%	5506	6396	86.08	6403	6403	100%
nginx	137	1148	11.93%	1109	1148	96.60%	1054	1148	91.81%	1154	1154	100%





### 6. Conclusion

□NOProbe: Fast, scalable, and less intrusive.

□ Multiple strategy

□5-byte CALL

□2-byte JMP combined with a NOP-padding.

Two algorithms to assign NOPs to probes.

□Last resort TRAP-based probe.

□Lock and Load: A protocol that can patch up to a basic block length safely without stopping the program.

□ Future direction:

□More strategies could be added.

□For safe probe removal, URCU (User-space Read Copy Update) could be used.

