



Performance analysis of real time embedded systems with space and time partitioning

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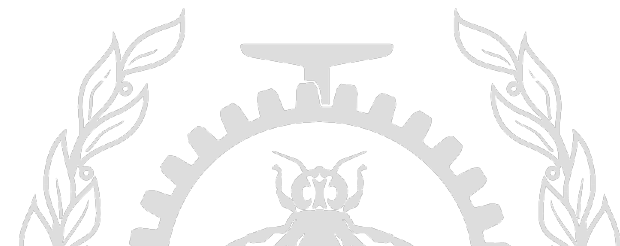
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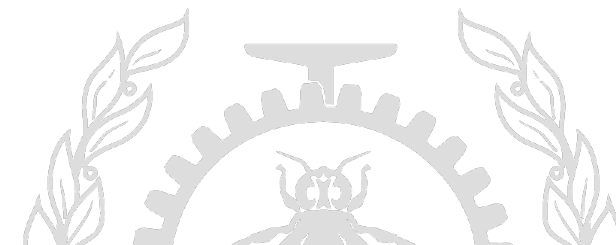
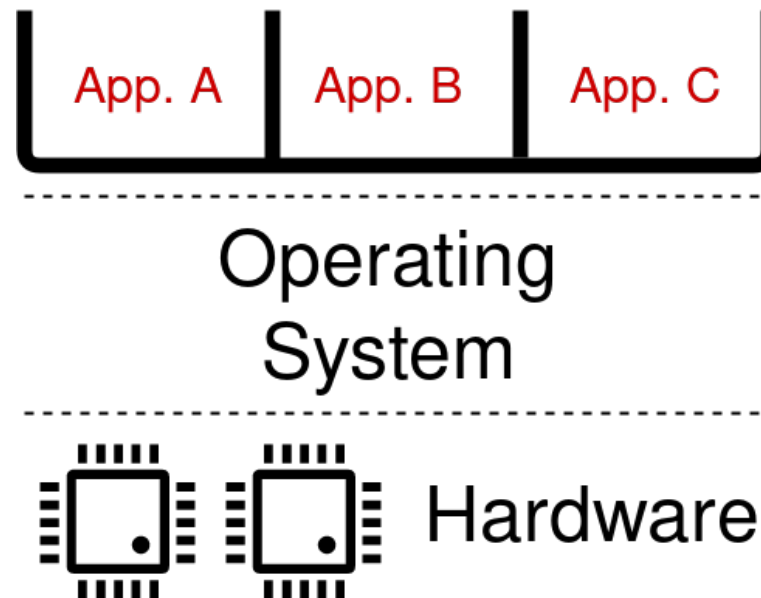
Agenda

- Space and Time partitioning with ARINC 653
- Performance in real time systems
- Analysis of ARINC 653 traces
- Conclusion



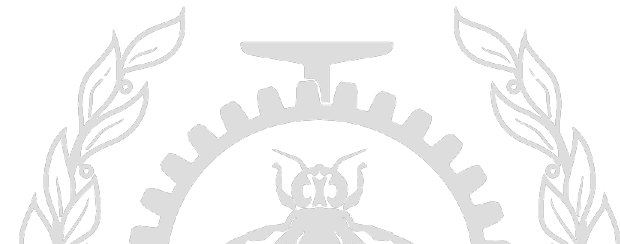
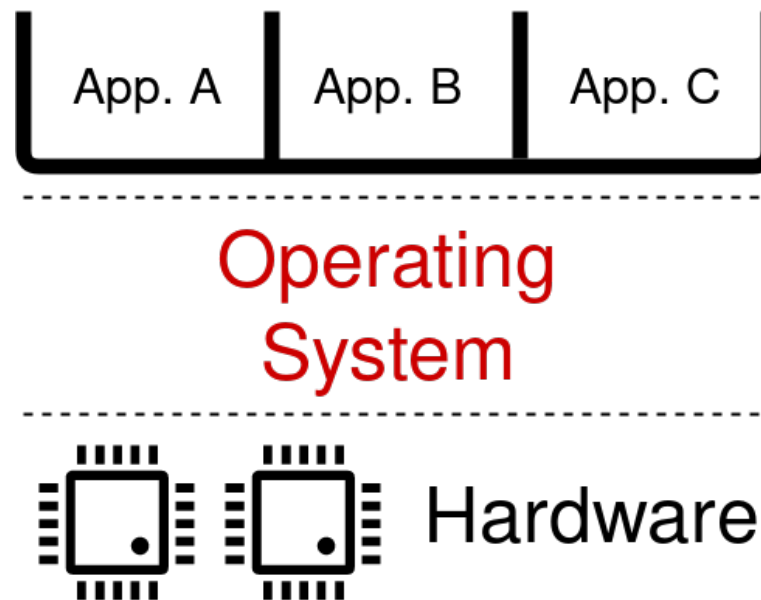
Space and time partitioning

- In **safety critical systems**, modules with different **criticality levels** may cohabit using the **same hardware** resources.
- In avionics, this trend is known as **Integrated Modular Avionics (IMA)**.
- Multiple applications may end up sharing the same processor.



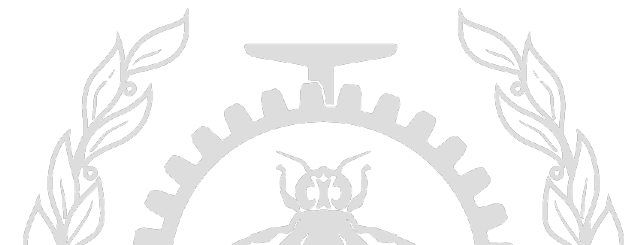
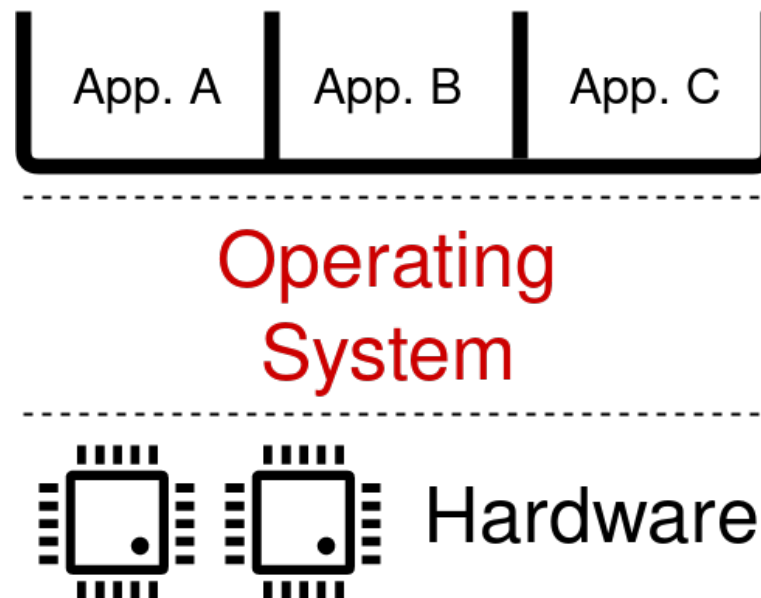
Space and time partitioning

- The operating system has to **isolate** the applications.
- Applications are isolated using space and time partitioning.
 - Space partitioning: Restriction of **memory** between partitions
 - Time partitioning: Attribution of a **fixed scheduled** to each partition.



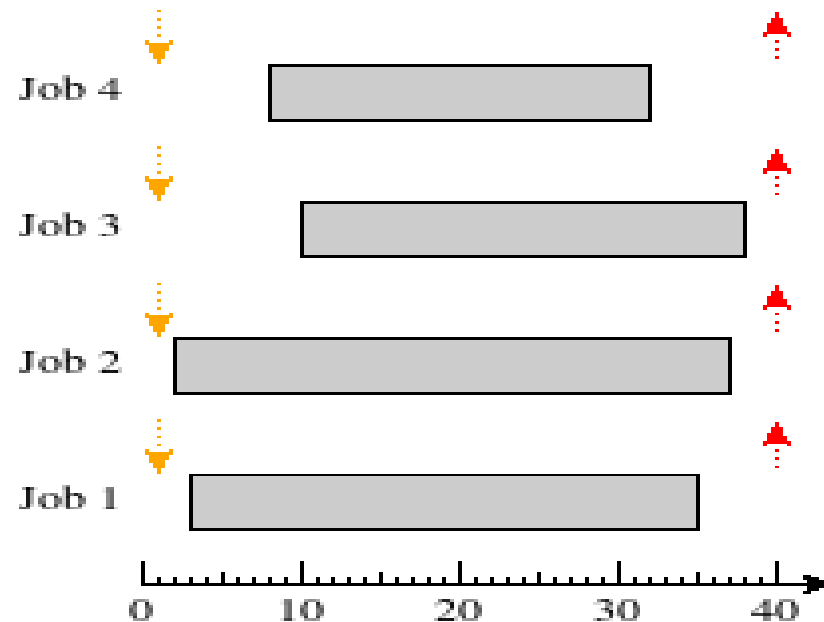
Space and time partitioning

- The operating system has to **abstract** hardware resources, but applications still require common services implemented via hardware (timer, file I/O, etc).
- A common API agreed and used by every contributor would be useful.
- In commercial avionics, this is the **APEX API** of the ARINC 653 standard.



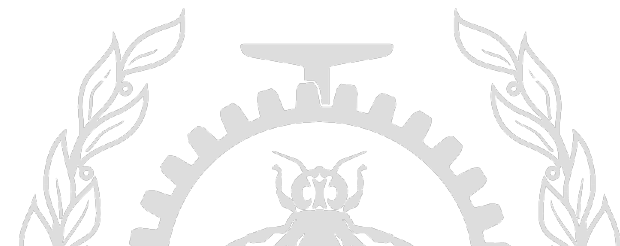
Performance in real time systems

- Safety-critical real time systems are subject to very stringent **temporal constraints**.
- Performance is not only a matter of speed, but also of **determinism** and **timeliness**.



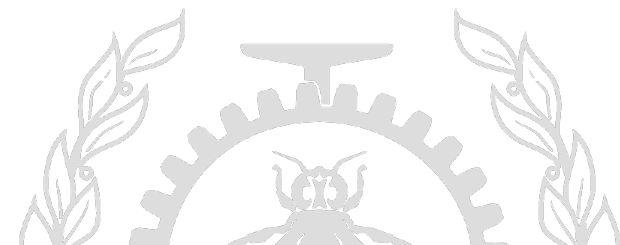
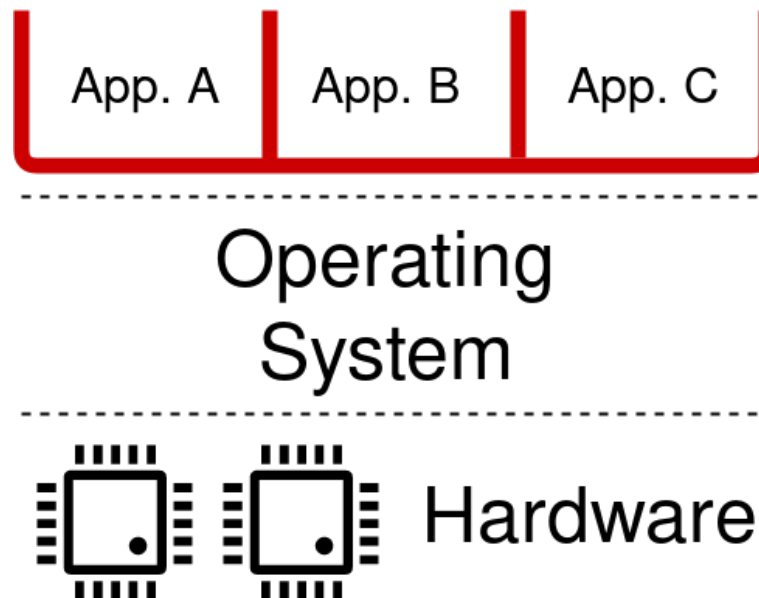
Performance in real time systems

- Troubleshooting performance related issues in real time systems has to be done with **minimal overhead**.
- Issues might occur once in a while and will be hard to reproduce.
- **Tracing** is the appropriate solution for this.



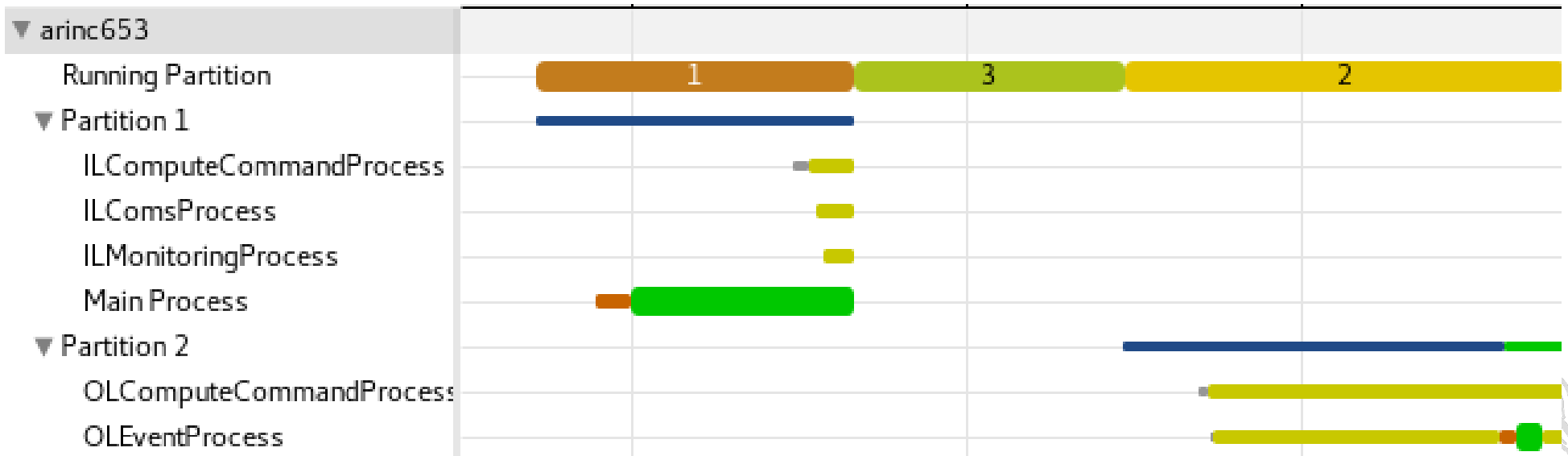
Tracing

- Tracing operating systems with space and time partitioning is not different from traditional operating systems.
- The main difference is **partitions**.
- Comparable to **containers** or **Linux control groups**, with strict time constraints.



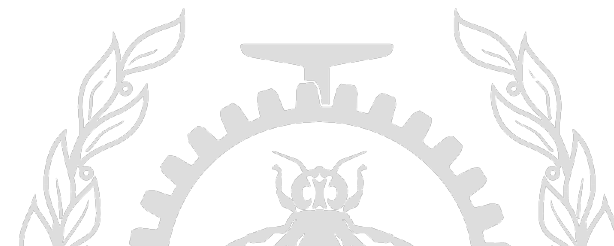
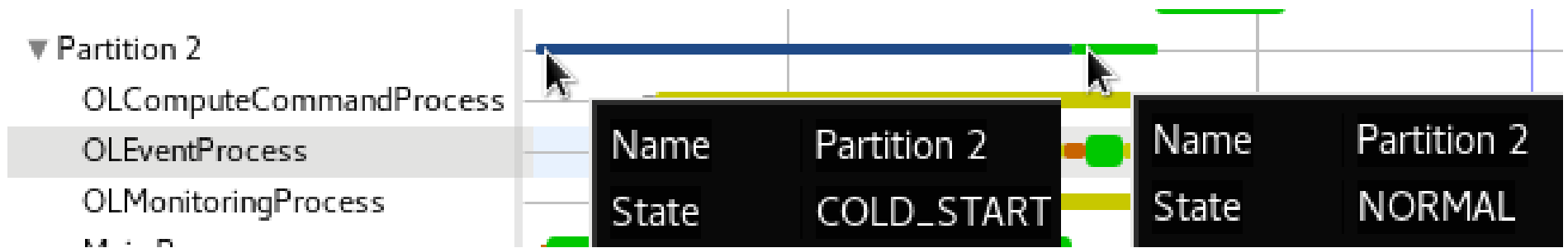
Trace analysis

- An equivalent of the **Control Flow View** in Trace Compass was developed for ARINC 653 operating systems.
- Using a set of events similar to those in Linux, this timeline of the processes can be created.



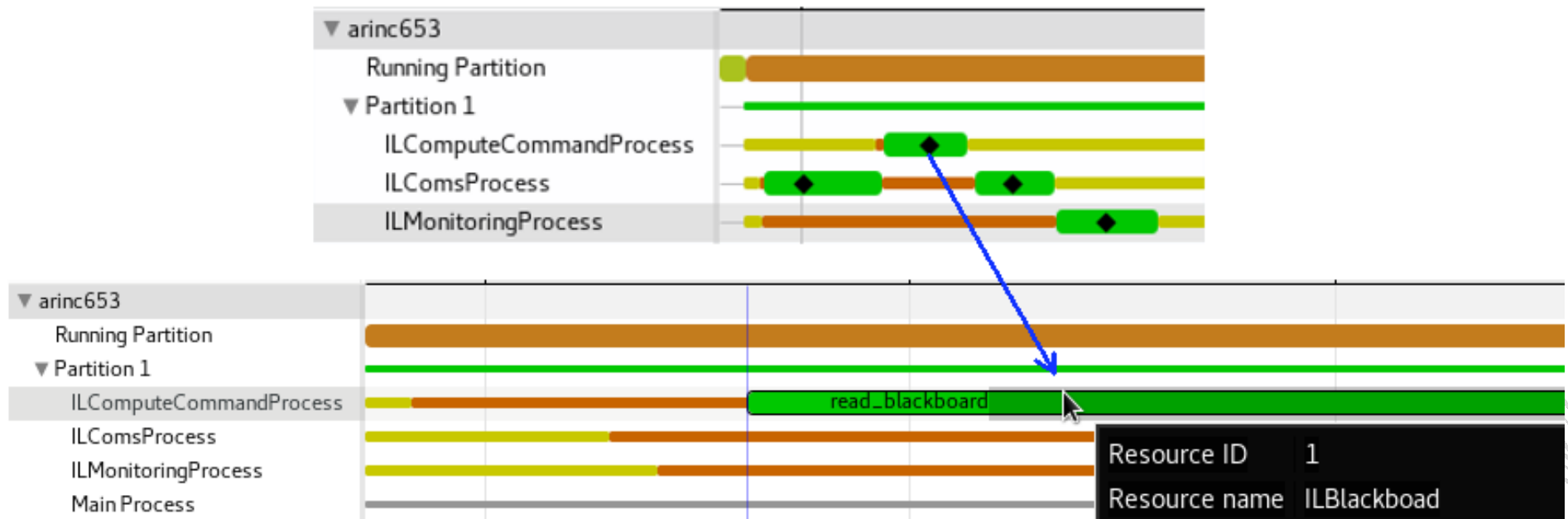
Trace analysis

- ARINC 653 defines three **partition operating modes**.
 - WARM_START, COLD_START, NORMAL
- The partition operating mode is displayed on the partition line.



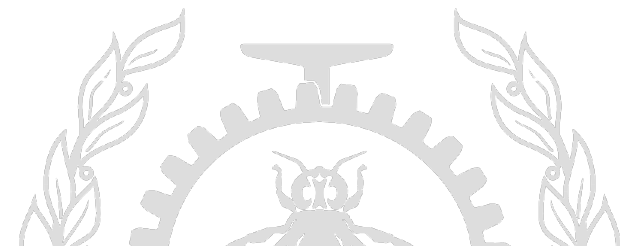
Trace analysis

- Applications created for an ARINC 653 operating system will work closely with the APEX API.
- **APEX calls** are displayed using the incoming Trace Compass **overlays**.
- Additional details are provided in the tooltip.



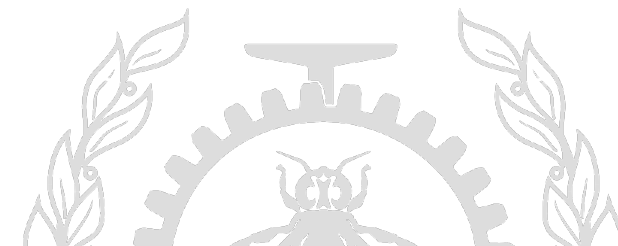
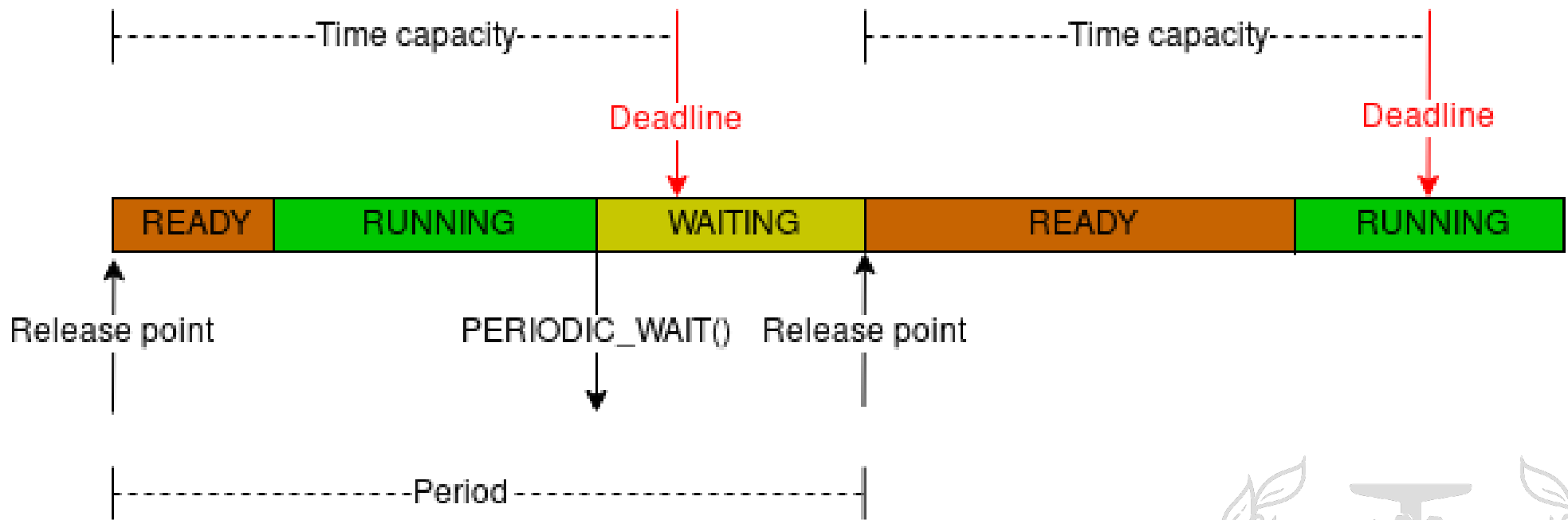
Trace analysis

- How can we help developers detect and remedy to performance issues in ARINC 653 operating systems?
 - **Deadline misses**
 - Latencies
- Detecting real time jobs.
- Showing job executions.
- Show the origin of issues.



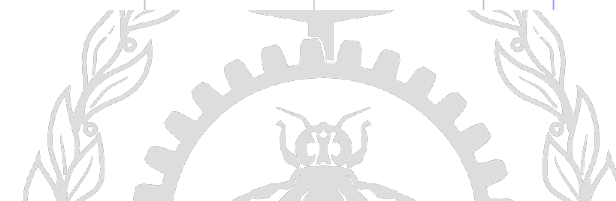
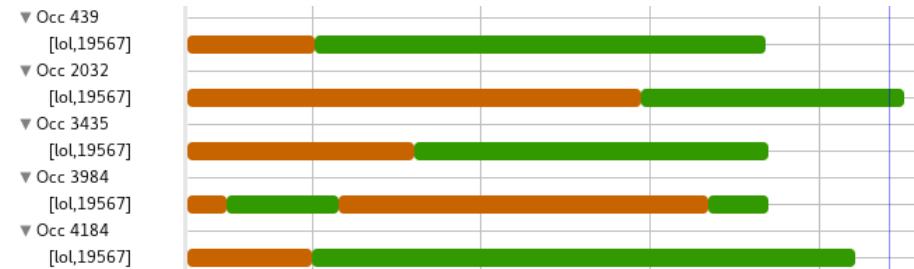
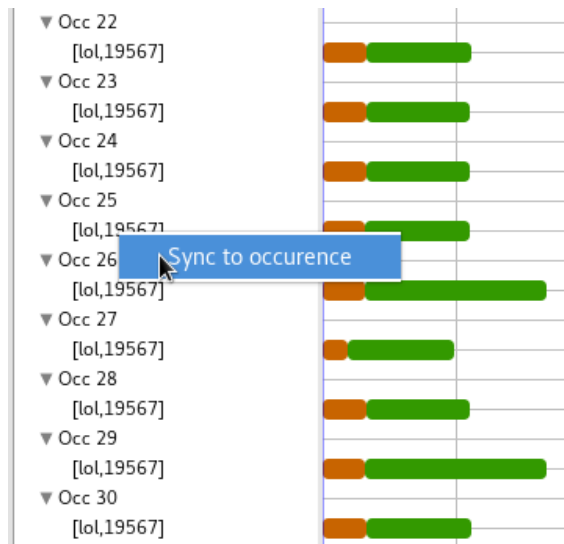
Detecting deadline misses

- ARINC 653 defines time management for processes. Each periodic process is associated with a **time capacity**, a **period** and a **deadline**.



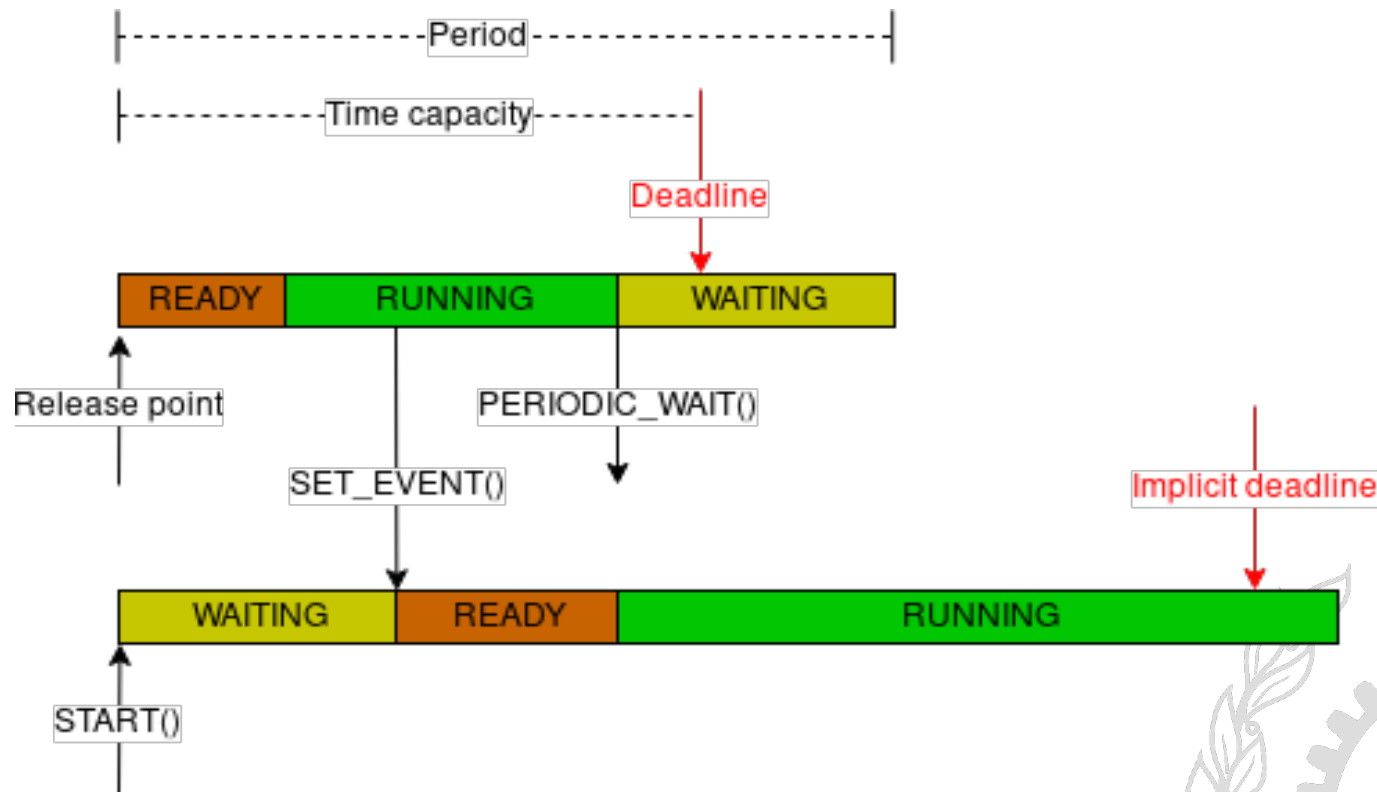
Detecting deadline misses

- Simple periodic processes follow a pattern easily detectable if **APEX calls** are traced.
- Aperiodic processes with simple execution patterns can also be matched.
- A list of every job (occurrence of a task) for a specific process can be generated from the Control Flow View.



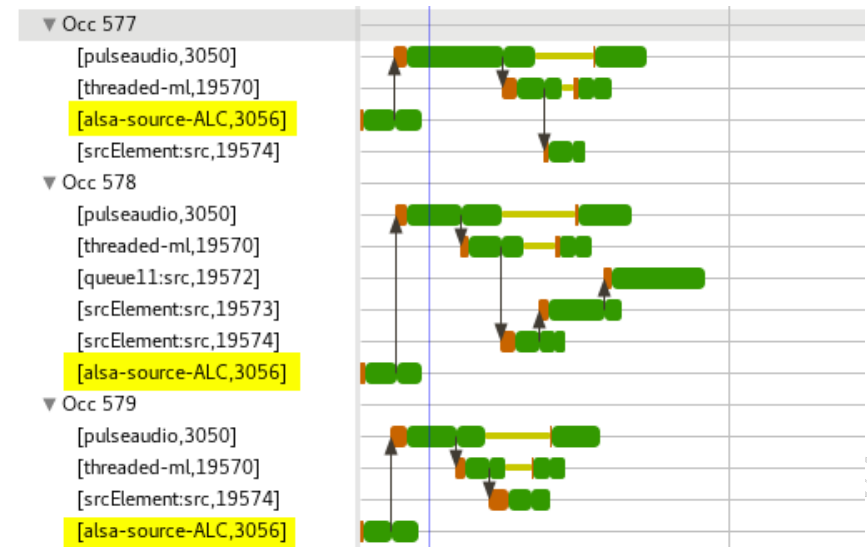
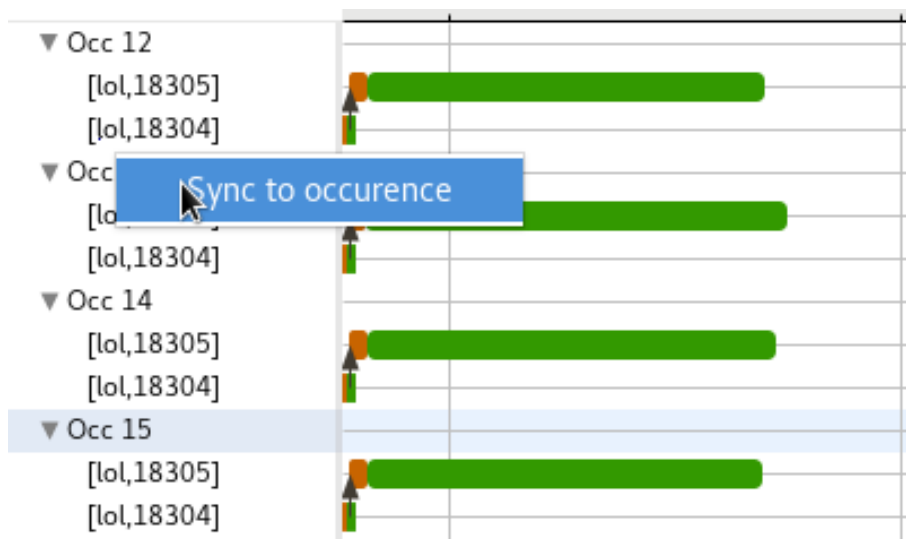
Detecting deadline misses

- Periodic processes often release jobs in the system. We must also detect if any job released missed a deadline.
- The released job deadline might not be explicit in the trace.



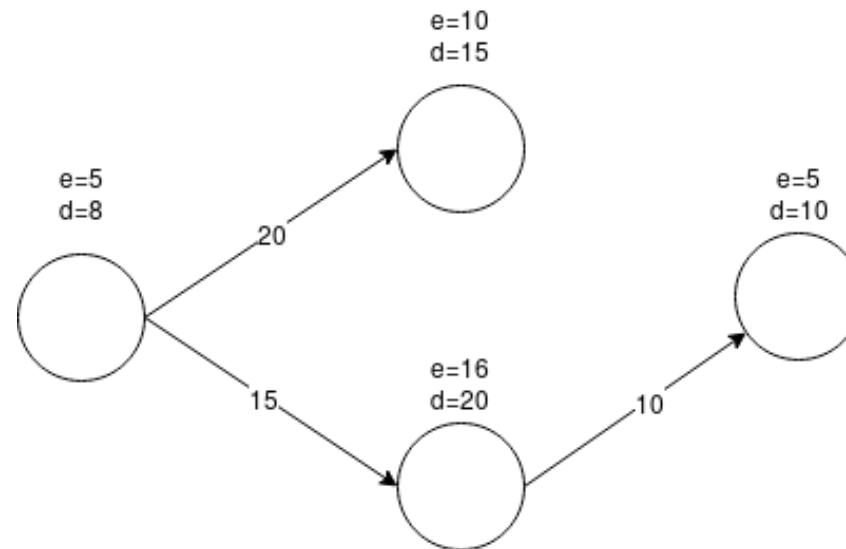
Detecting deadline misses

- The process that released the jobs can be detected as a periodic process.
- We can follow the **outgoing vertical edges** in the execution graph of the process that releases the jobs to build a sub graph.
- The jobs can be listed and filtered depending on their execution time.



Limitations

- Different types of jobs with different execution times might be released from the same process.
- Filtering is not as efficient.
- Real time task models in schedulability analysis can represent complex tasks composed of multiple jobs.



Conclusion

- **ARINC 653** is a standard for space and time partitioning operating systems.
- A plugin was developed to **analyze** their traces.
- We propose real time job detection techniques to find **deadline misses**.



Source: Airbus A380, Wikipedia

Questions?

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